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Deformation Behavior of Screen Mesh in Screen Printing and Its Effect on Printing Results

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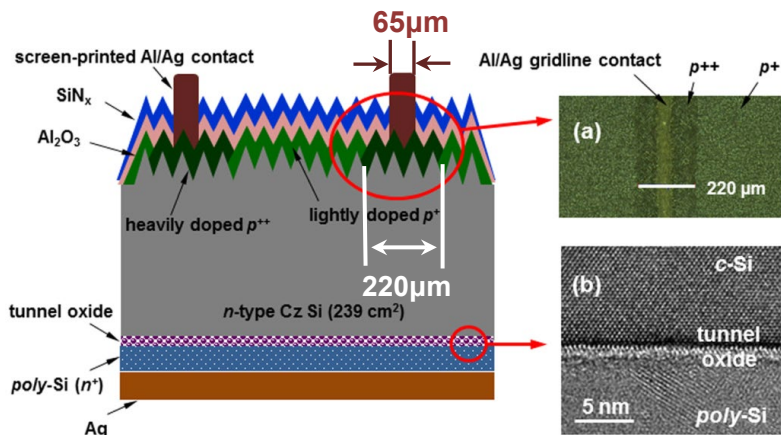
Outline

- Introduction
- Experiment
- Simulation
- Conclusions

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Positioning accuracy in screen printing



Y. Tao, et al, "High-efficiency selective boron emitter formed by wet chemical etch-back for n-type screen-printed Si solar cells" Appl. Phys. Lett. 110, p.021101 (2017)

Trend: finger width



ITRPV 14th edition, March 2023 key findings & report presentation

**Need accurate metallization
onto selective emitter**

**Finer finger 15µm &
Alignment precision 5µm @ 2033**

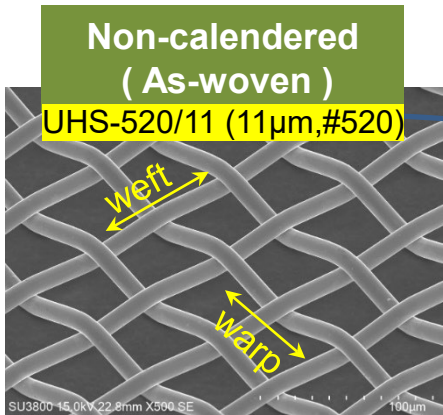
Positioning accuracy in screen printing is an essential key to improving the performance of silicon solar cells.

Factors affecting positioning accuracy of screen printing

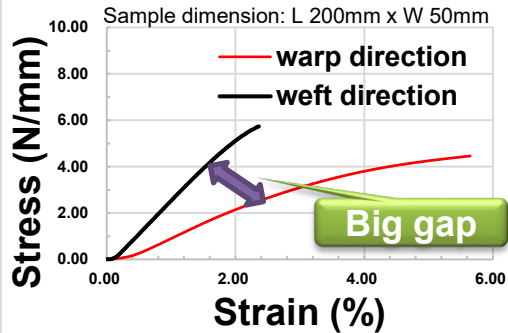
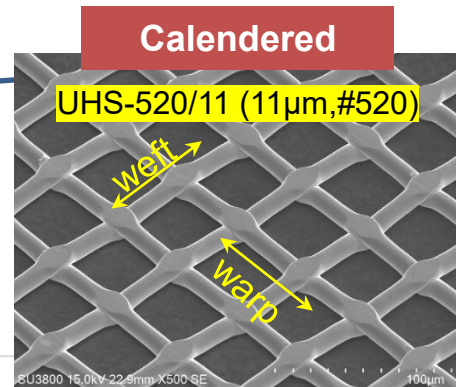
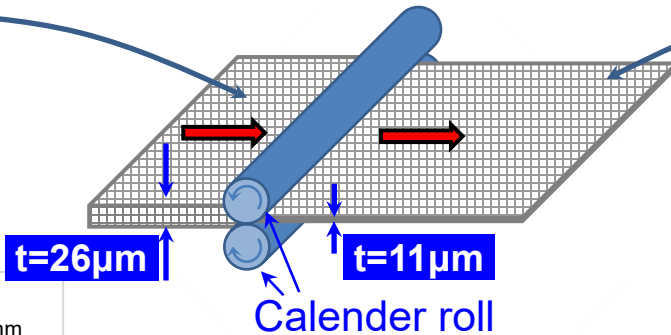
- Environmental conditions
 - temperature & humidity
- Mechanical accuracy of printing equipment
 - vision system for the alignment mechanism
 - mechanical positioning of printing system
- Uniformity of mechanical properties of the screen

We focus on mesh deformation during printing, which causes misalignment of metallization.

How to make the mechanical properties of mesh uniform



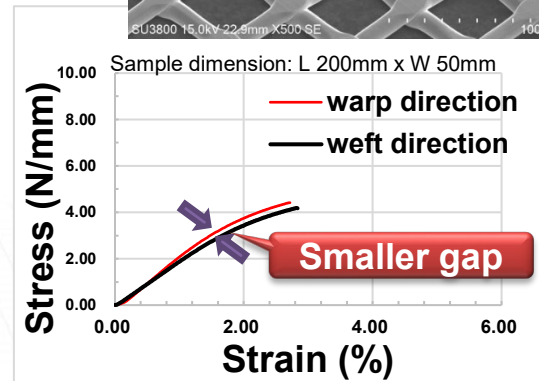
Calendering



Stress – Strain curve of UHS 520/11 Non-calendered(As-woven) mesh (t=26µm)

To improve the homogeneity of the mechanical properties of the mesh

The warp direction and weft one aligned to have the same mechanical properties



Stress – Strain curve of UHS 520/11 Calendered mesh (t=11µm)

Motivation

- This study aims to analyze;
 - The printed positioning accuracy of screen printing experiments and simulations conducted under the same conditions to investigate the effect of screen mesh deformation
 - The effect of calendering process

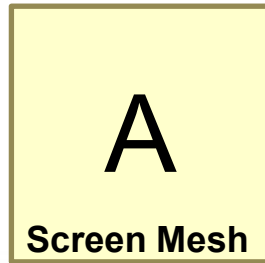
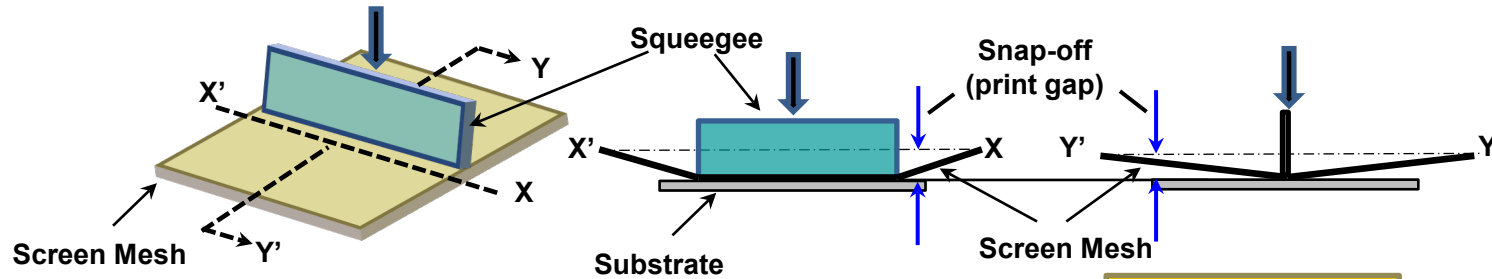
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- Simulation
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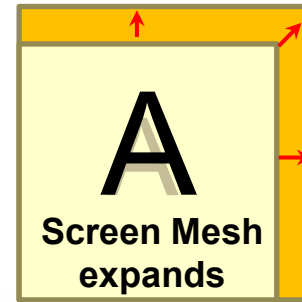
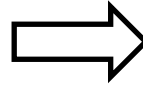
Screen printing experiments

- Screen mesh
 - UHS-520/11 (11 μ m,#520)
 - Non-calendered, t=26 μ m
 - Calendered, t=11 μ m
 - Mesh bias angle: 22.5 degrees
 - Mesh on-screen frame: Direct-stretching
- Screen printing parameters
 - Print speed: 50mm/sec
 - Printing pressure: 45.3N
 - Squeegee length: 170mm
 - Print gap: 1.3mm

Screen mesh behavior in screen printing



squeegee press mesh down

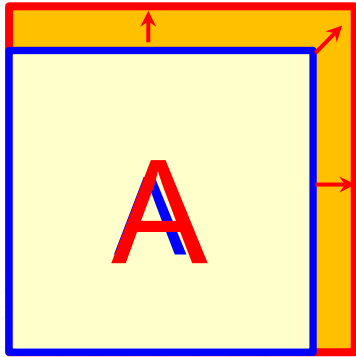


A screen mesh is deformed as a squeegee presses down

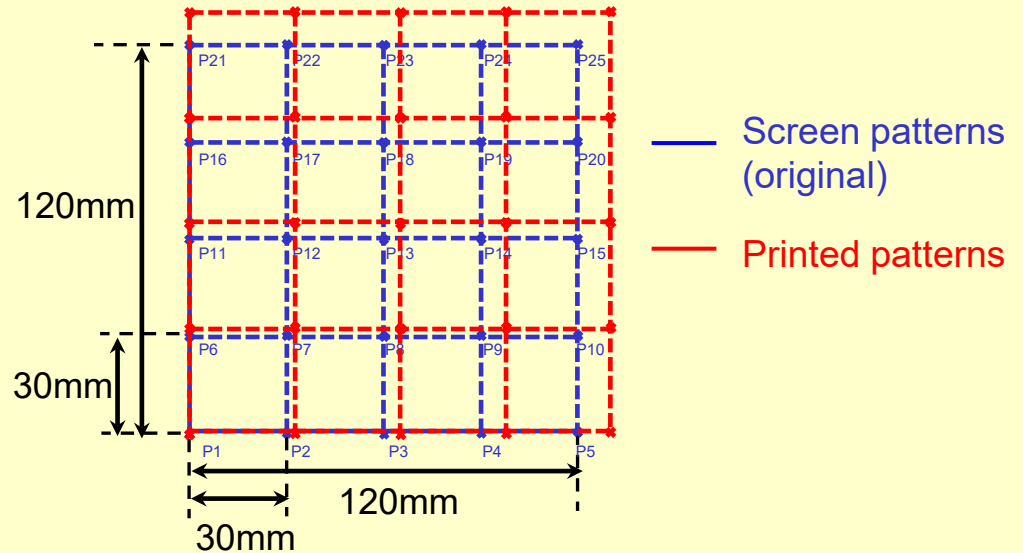
Patterns printed on a substrate become larger than an original ones on the screen

Image of screen and printed patterns

Pattern printed on a substrate is expanded and deformed

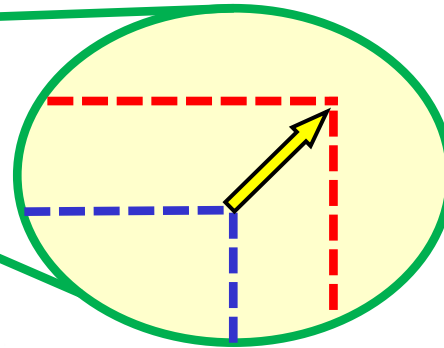
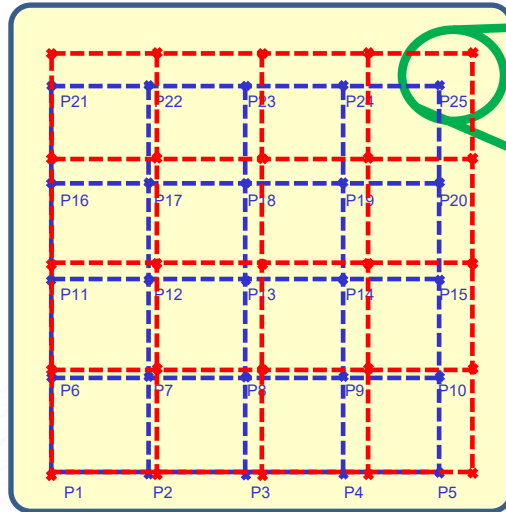


Printed patterns (25 points)



Definition of “Displacement”

$$\text{Displacement} = |\text{Printed} - \text{Screen}|$$



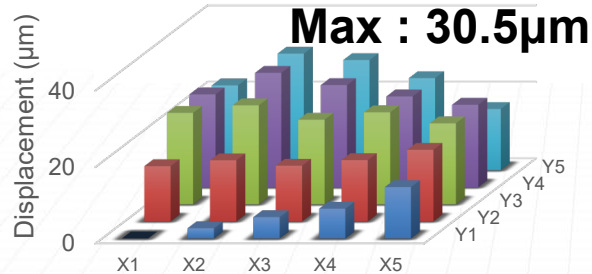
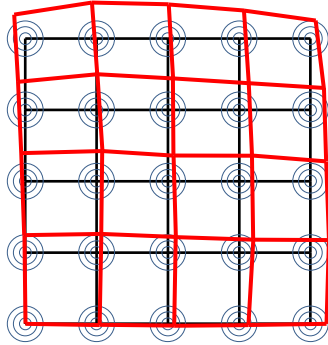
- Screen patterns (original)
- Printed patterns

How far the points move from the original positions?

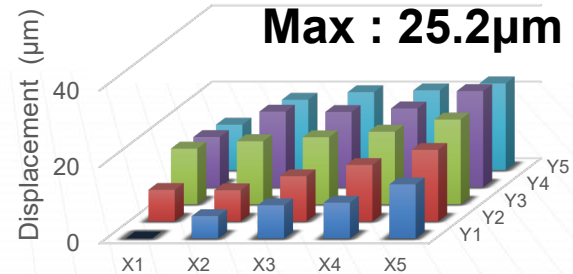
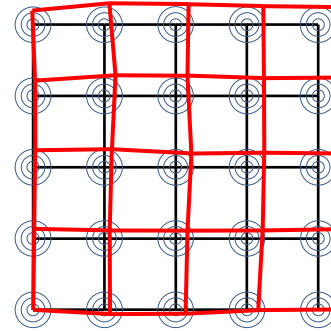
Results - Displacement

The non-calendered mesh is more deformed than the calendered one.

Non-calendered



Calendered

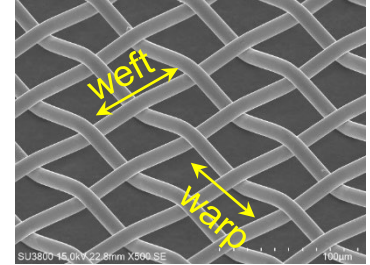


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Simulation – FEM analysis

- Mesh : Orthotropic material
 - warp and weft
- Stress(σ)/Strain(ε) relationship equation for orthotropic materials



$$\begin{pmatrix} \varepsilon_T \\ \varepsilon_L \\ \varepsilon_{TL} \end{pmatrix} = \begin{bmatrix} 1/E_T & -\nu_{LT}/E_L & 0 \\ -\nu_{LT}/E_L & 1/E_L & 0 \\ 0 & 0 & 1/G_{LT} \end{bmatrix} \begin{pmatrix} \sigma_T \\ \sigma_L \\ \tau_{TL} \end{pmatrix}$$

(T=x, L=y)

ε : Strain

σ : Stress

τ : Shearing stress

ν : Poisson's ratio

E : Modulus of longitudinal elasticity

G : Shearing modulus

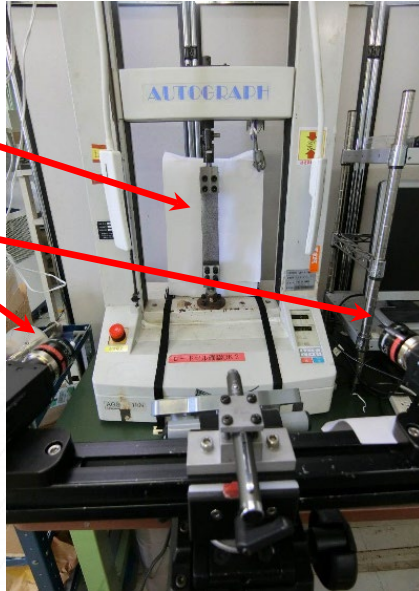
- E, ν , and G can be obtained by tensile tests in the warp, weft, and 45-degree directions of the mesh.

Tensile test of mesh

The in-plane stress-strain curves of the meshes in the direction of warp, weft, and 45degree were measured by the “image correlation method”

Test sample

Cameras

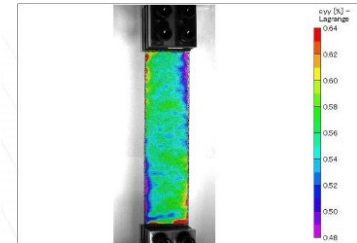
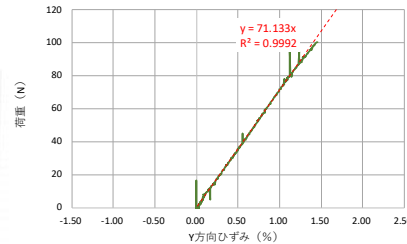


Test specimen

UHS-520/11 (11 μ m,#520), 6 pieces (without emulsion)

a) Non-calendered mesh (t=26 μ m) x 3 directions (0° ,45° ,90°)

b) calendered mesh (t=11 μ m) x 3 directions (0° ,45° ,90°)



Calculated E , ν , and G

The following parameters are calculated from the results of tensile tests of the meshes

	$E_{L(0^\circ)}$ ^{*1} (MPa)	$E_{T(90^\circ)}$ ^{*1} (MPa)	ν_{LT} (-)	G_{LT} ^{*2} (MPa)
Non-calendered	139.48	268.08	0.1892	0.1131
Calendered	272.94	235.42	0.2952	0.8339

*1 Elastic modulus per width of 1mm

*2 G_{LT} is calculated from the following equation

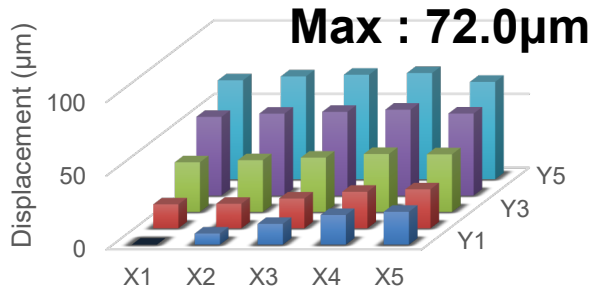
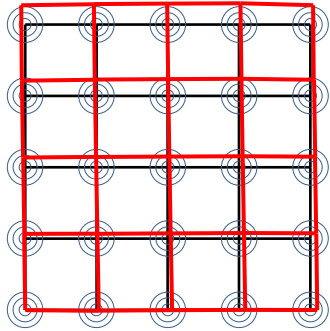
$$\frac{1}{G_{LT}} = \frac{4}{E_{45^\circ}} - \left(\frac{1}{E_L} + \frac{1}{E_T} - \frac{2\nu_{LT}}{E_L} \right)$$

The coordinate of each point of the deformed pattern is simulated by FEM analysis using these values on the mesh.

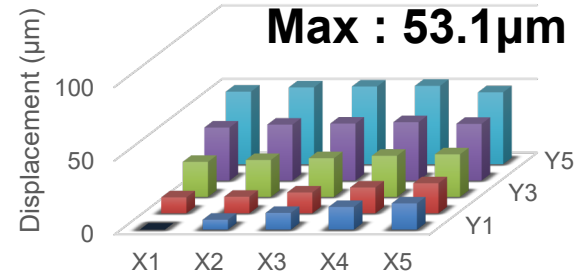
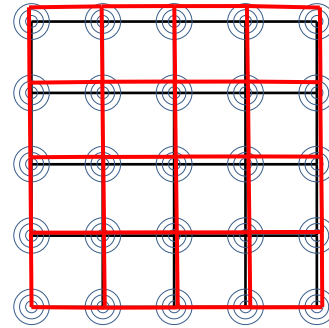
Simulation results - Displacement

The non-calendered mesh is more deformed than the calendered one.

Non-calendered



Calendered



Summary of results

Quantitative analysis of the mechanical behavior of the non-calendered and calendered mesh samples revealed a significantly higher degree of deformation in the former. [The calendering process can improve the mechanical uniformity of the as-woven mesh.](#)

	Displacement (μm)	
	Non-calendered	Calendered
Printing result	30.5	> 25.2
Simulation	72.0	> 53.1

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Conclusions

1. Based on the experiments, the calendered mesh shows less pattern deformation compared to the non-calendered one. This is because calendering aligns the warp and weft at the stress-strain curve.
2. The simulation demonstrates a similar trend to the experiment, but its magnitude is greater than that observed in the experiment.
3. To make a comparison with the results of other experimental conditions, further improvements are required for the simulation.

Thank you for your attention